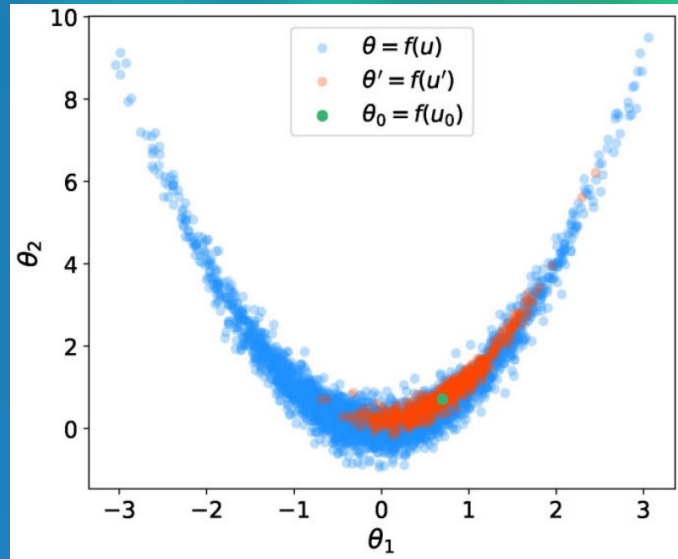


Accelerating astronomical and cosmological inference with preconditioned Monte Carlo

(2022, MNRAS, 516, 2, 1644-1653)

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Probability density integrals from a random sample

- Expected value of \mathbf{x} is:

$$E(\mathbf{x}) = \int \mathbf{x} p(\mathbf{x}) d\mathbf{x} \simeq \frac{1}{N} \sum_i \mathbf{x}_i$$

If the points \mathbf{x}_i are drawn according to the $p(\mathbf{x})$ distribution

- Expected value of any function \mathbf{f} of \mathbf{x} is also easy to calculate

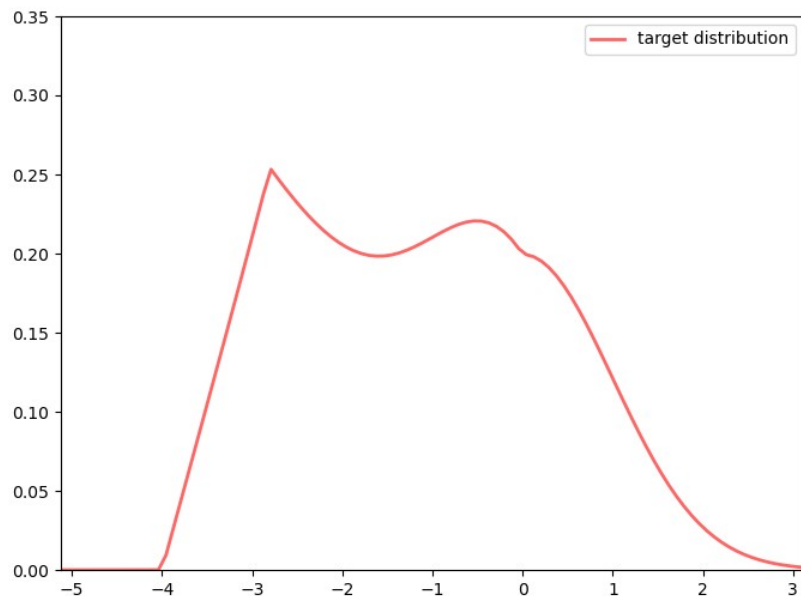
$$E(\mathbf{f}) = \int \mathbf{f}(\mathbf{x}) p(\mathbf{x}) d\mathbf{x} \simeq \frac{1}{N} \sum_i \mathbf{f}(\mathbf{x}_i)$$

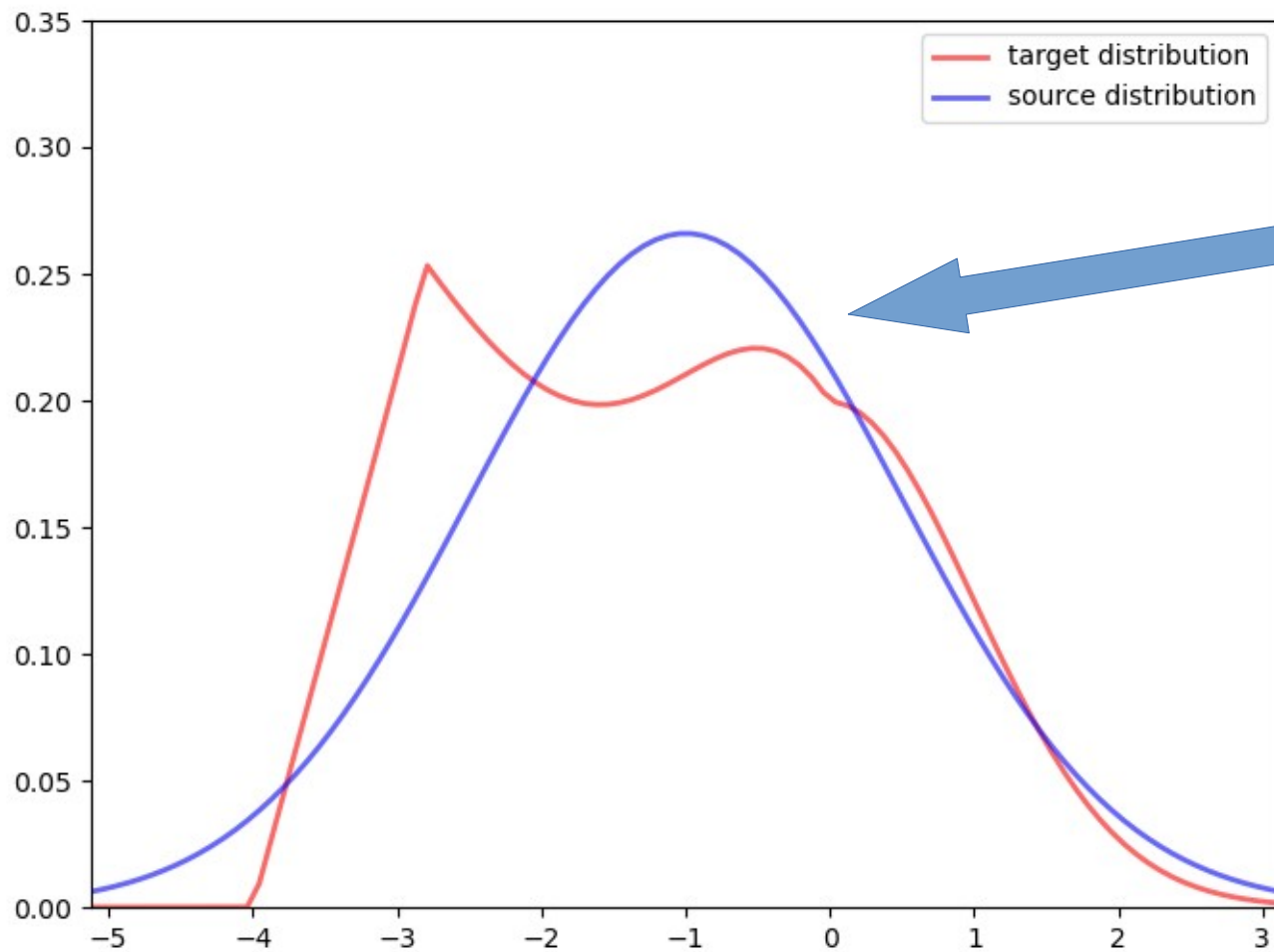
If the points \mathbf{x}_i are drawn according to the $p(\mathbf{x})$ distribution

Importance sampling

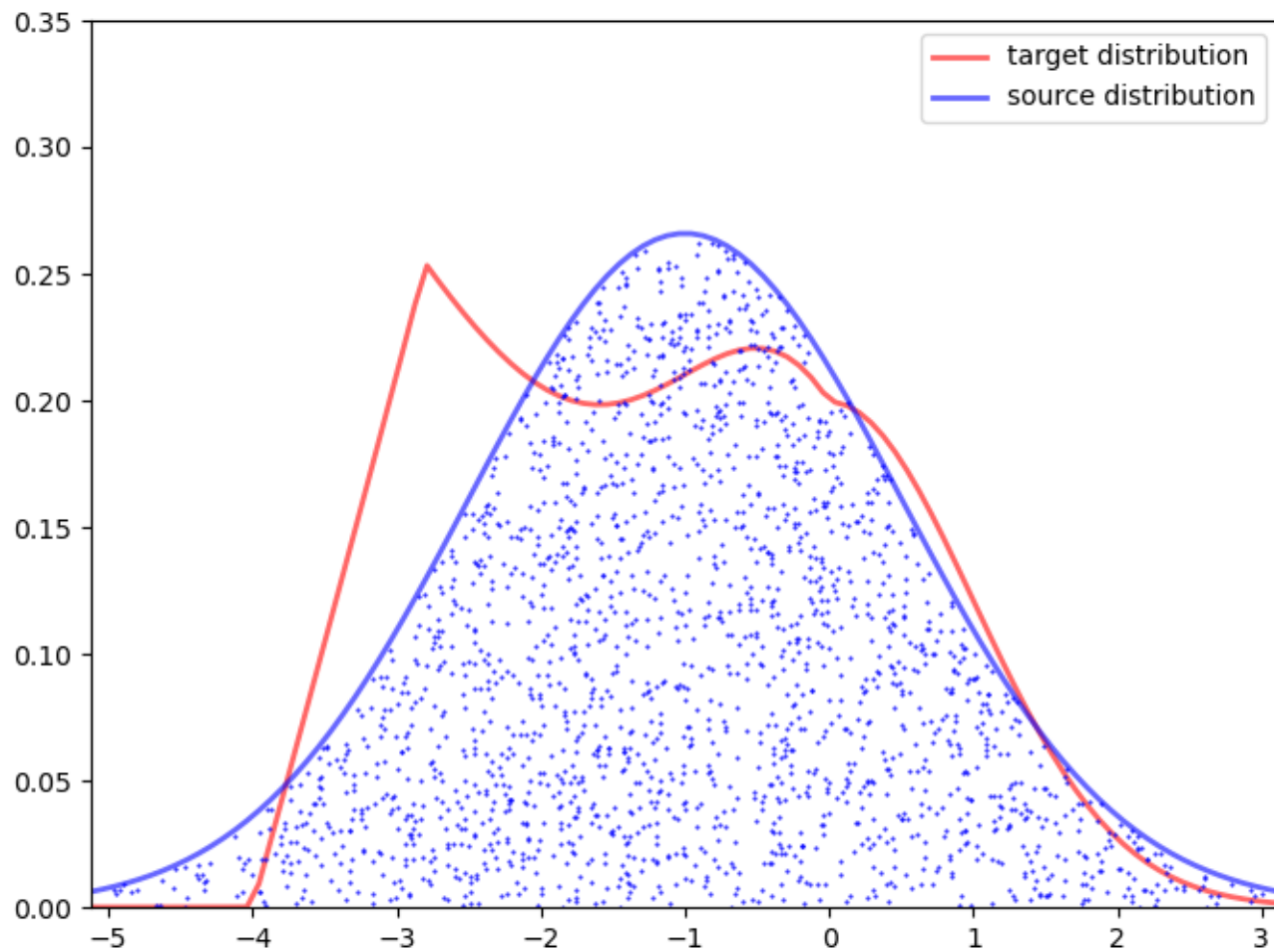
Problem:

$p(x)$ is a probability density, and we need a random sample from it,
For example, to calculate something for it (expected value, percentiles, or any integral)

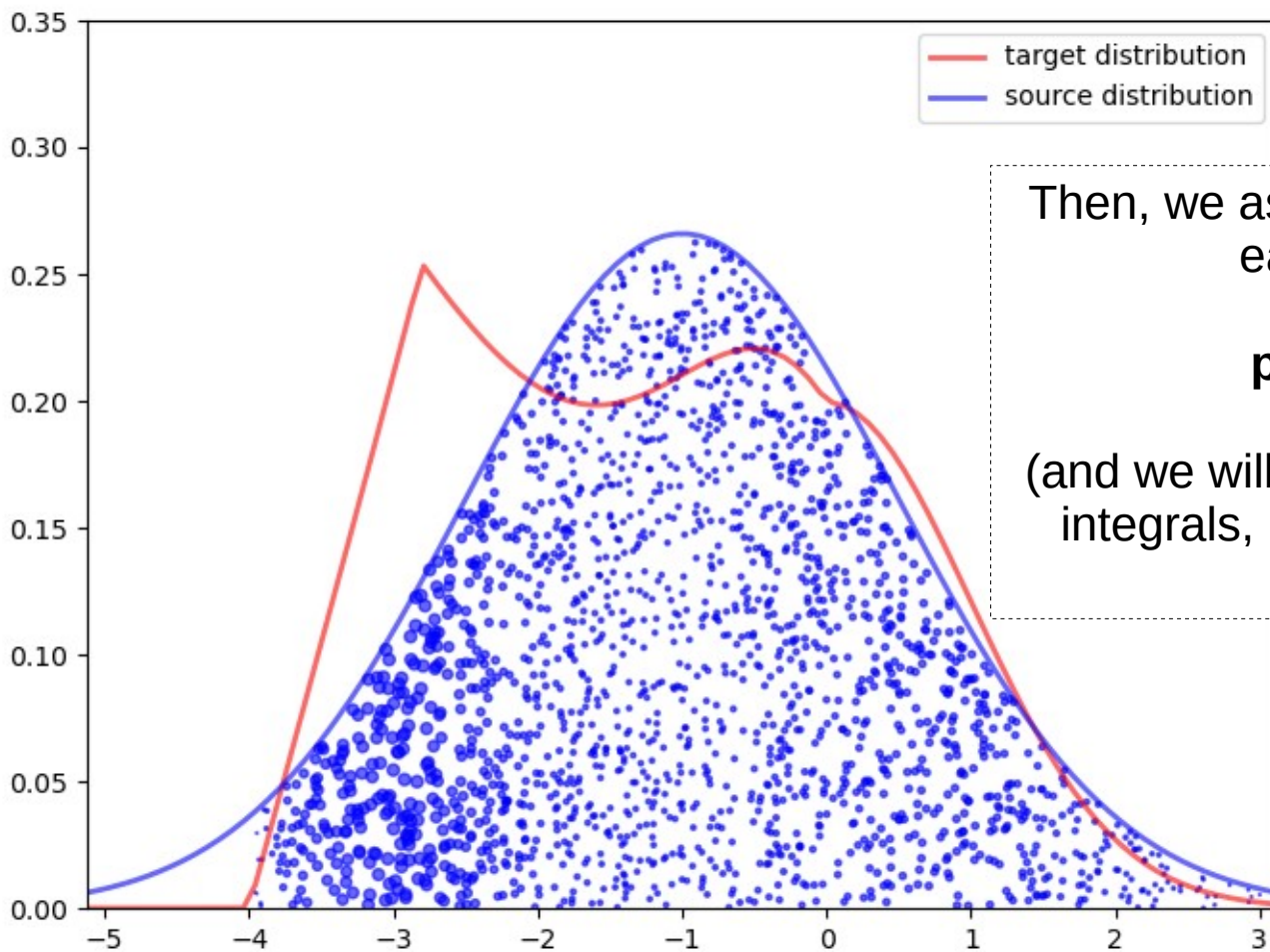




We choose any „similar” function, from which it is easy to get a random sample from:
 $q(x)$



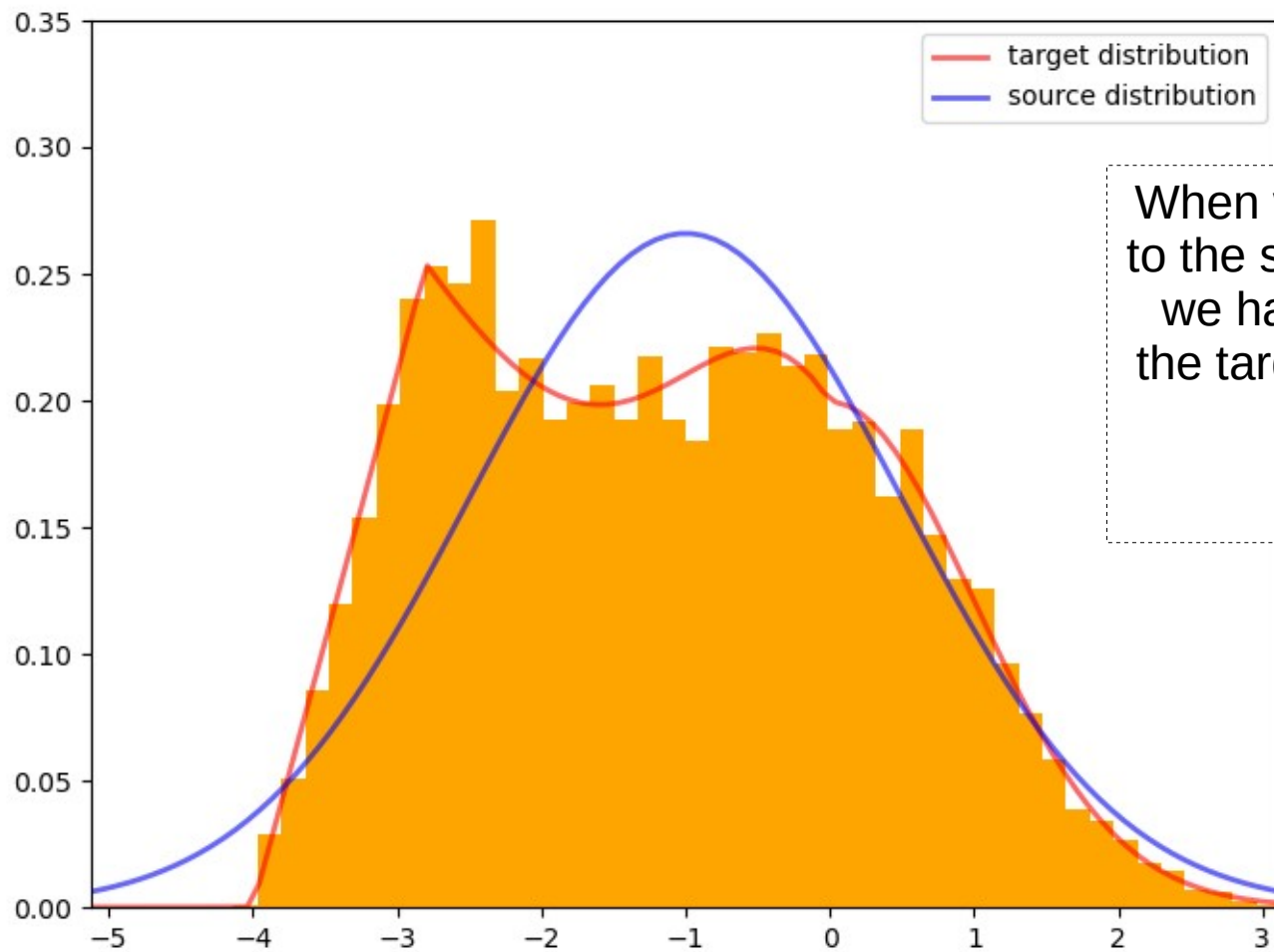
We draw a sample
from the
distribution q



Then, we assign „**weights**” for each point

$$p(x) / q(x)$$

(and we will use this weight for integrals, histograms, etc.)



When we add the weights to the sample, it looks as if we have a sample from the target $p(x)$ distribution

Probability density integrals in importance sampling


- Expected value of \mathbf{x} is:

$$E(x) = \int x p(x) dx = \int x \frac{p(x)}{\rho(x)} \rho(x) dx = \int [x w(x)] \rho(x) dx$$

$$\simeq \frac{1}{N} \sum_i [x_i w(x_i)] = \frac{1}{N} \sum_i [x_i w_i], \text{ where } w(x) = \frac{p(x)}{\rho(x)}$$

- Expected value of any function \mathbf{f} of $\boldsymbol{\theta}$ is also easy to calculate

$$E_p[f(\theta)] = \int f(\theta) w(\theta) \rho(\theta) d\theta \bigg/ \int w(\theta) \rho(\theta) d\theta$$

normalization 

$$\rightarrow \frac{1}{N} \sum_i [f(\theta_i) w(\theta_i)]$$

If the points θ_i are drawn according to the $p(\theta)$ distribution

Notation

Bayes formula:

$$P(\theta | D, M) = \frac{P(D | \theta, M) P(\theta | M)}{P(D | M)}$$

$$\text{posterior} \quad \mathcal{P}(\theta) = \frac{\text{likelihood} \quad \text{prior} \quad \mathcal{L}(\theta) \pi(\theta)}{\text{evidence} \quad \mathcal{Z}}$$

We could use importance sampling to sample from the posterior



01 Draw sample from: $\pi(\theta)$

02 We need sample from: $\mathcal{L}(\theta) \pi(\theta)$

03 So, we weight sample with:
 $w(\theta) = \mathcal{L}(\theta) \pi(\theta) / \pi(\theta) = \mathcal{L}(\theta)$

04 This is very **inefficient**, if
likelihood is significantly
different from the prior

Sequential Monte Carlo (SMC)

It is similar to the importance sampling, but in couple of stages

$$p_1(\theta) = \pi(\theta)$$

$$p_T(\theta) = \pi(\theta) \mathcal{L}(\theta)$$

$$p_t(\theta) \propto \pi(\theta) \mathcal{L}(\theta)^{\beta_t}, \quad t = 1, \dots, T$$

$$\beta_1 = 0 < \beta_2 < \dots < \beta_T = 1$$

Sequential Monte Carlo (SMC)

Weight at every step:

$$w_t(\theta_t) = p_t(\theta_{t-1}) / p_{t-1}(\theta_{t-1})$$

So, the total, combined weight is:

$$w = w_1 w_2 \dots w_T = \frac{p_2}{p_1} \frac{p_3}{p_2} \dots \frac{p_T}{p_{T-1}} = \frac{p_T}{p_1}$$

We need some reshuffling / resampling of the sample

Step 1

(i) *Mutation*. The population of particles is moved from $\{\theta_{t-1}^k\}_{k=1}^N$ to $\{\theta_t^k\}_{k=1}^N$ using a *Markov transition kernel* $K_t(\theta'|\theta)$ that defines the next important sampling density

$$p_t(\theta') = \int p_{t-1}(\theta) K_t(\theta'|\theta) d\theta. \quad (4)$$

In practice, this step consists of running multiple short MCMC chains (i.e. one for each particle) to get the new states θ' starting from the old ones θ .

Step 2

(ii) *Correction*. The particles are reweighted according to the next density in the sequence. This step consists of multiplying the current weight W_t^k of each particle by the appropriate importance weight

$$w_t(\theta_t) = p_t(\theta_{t-1})/p_{t-1}(\theta_{t-1}). \quad (5)$$

Step 3

(iii) *Selection*. The particles are resampled according to their weights, which are then set to $1/N$. This can be done using *multinomial resampling* or more advanced schemes. The purpose of this step is to eliminate particles with low weight and multiply the ones with high weights.

Evidence

- We start from a sample from the prior and set the evidence to $Z=1$
- Evidence at every step can be updated, according to the sum of the weights (at every stage)

$$Z_t / Z_{t-1} = \sum_{k=1}^N W_{t-1}^k w_t(\theta_{t-1}^k)$$

Metropolis-Hastings

“standard algorithm”



- proposal step
- acceptance step

How we sample effectively?

- By using proposal distribution “close” to the target distribution

Alternative way

Use simple proposal distribution, but in changed parametrization

$$\mathcal{N}(u, 1) \leftarrow \text{proposal}$$

where

$$u = f(\theta)$$

“Preconditioning”



The authors approach

- Density estimation algorithm (from the current sample)
- Neural networks
 - Encoders (sample \rightarrow Gaussian)
 - Special network that is a *bijective* mapping, so:
 - sample \leftrightarrow Gaussian
- Sample in multidimensional Gaussian
 - easy and control-able and short!

Metropolis-Hastings

Optimal proposal
distribution for Gaussian
target distribution

$$\mathcal{N}(\theta, 2.38^2 \Sigma / ndim)$$

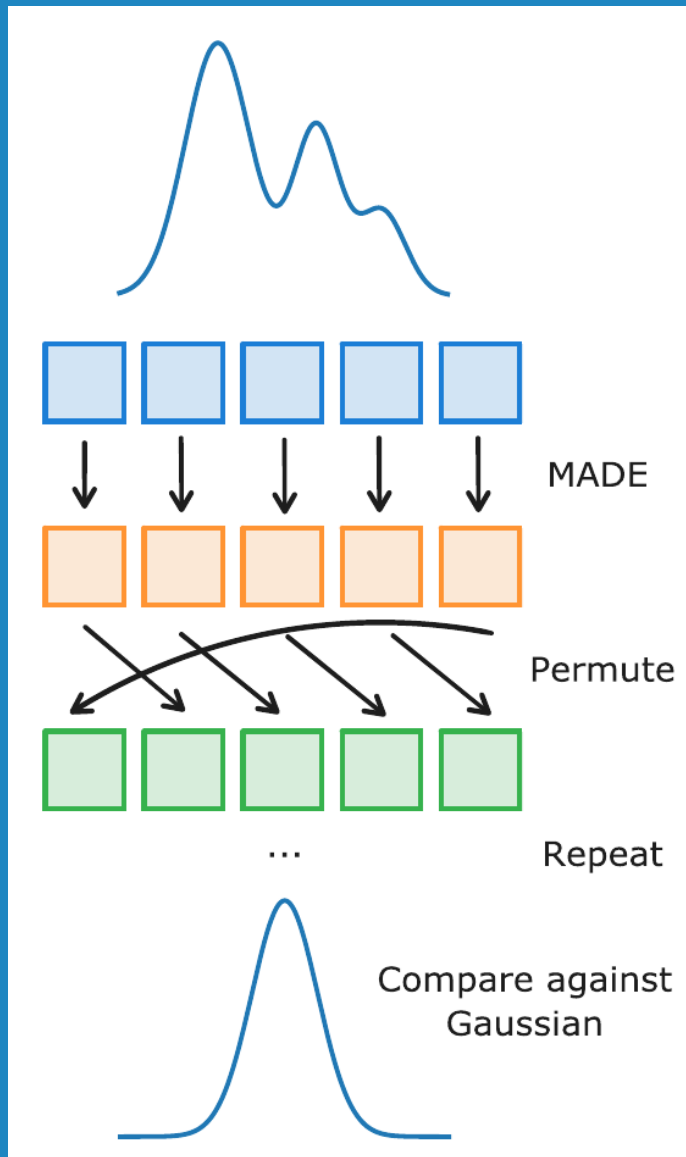
where Σ is covariance
matrix of the Gaussian

And then the acceptance
rate is 23.4%



“Normalizing flows”

- uses: Masked Autoregressive Density Estimator (MADE)
- maps any distribution into multidimensional Gaussian

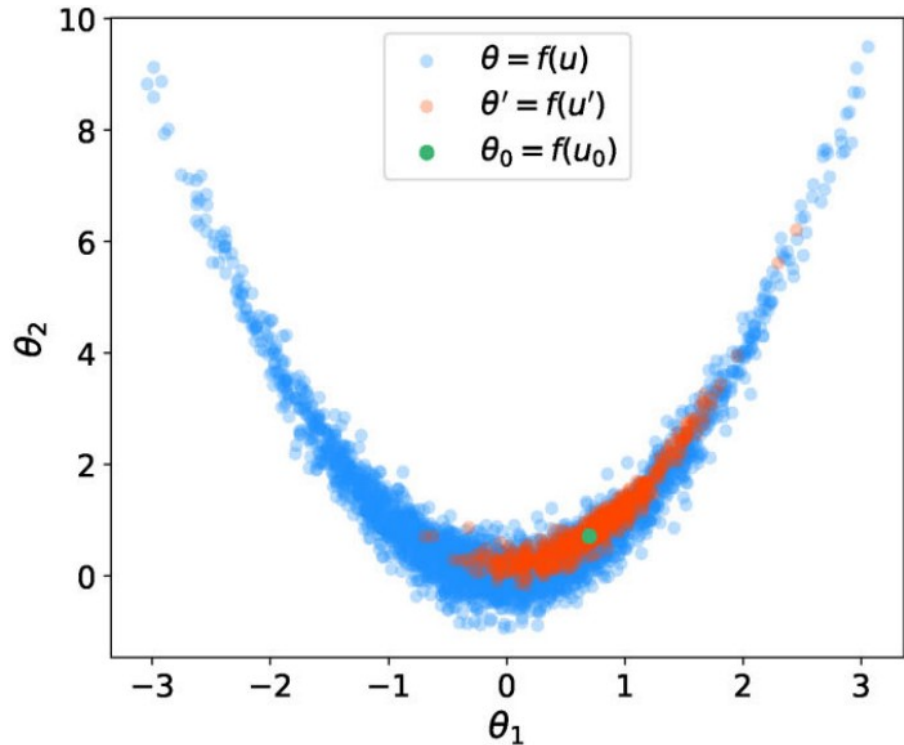
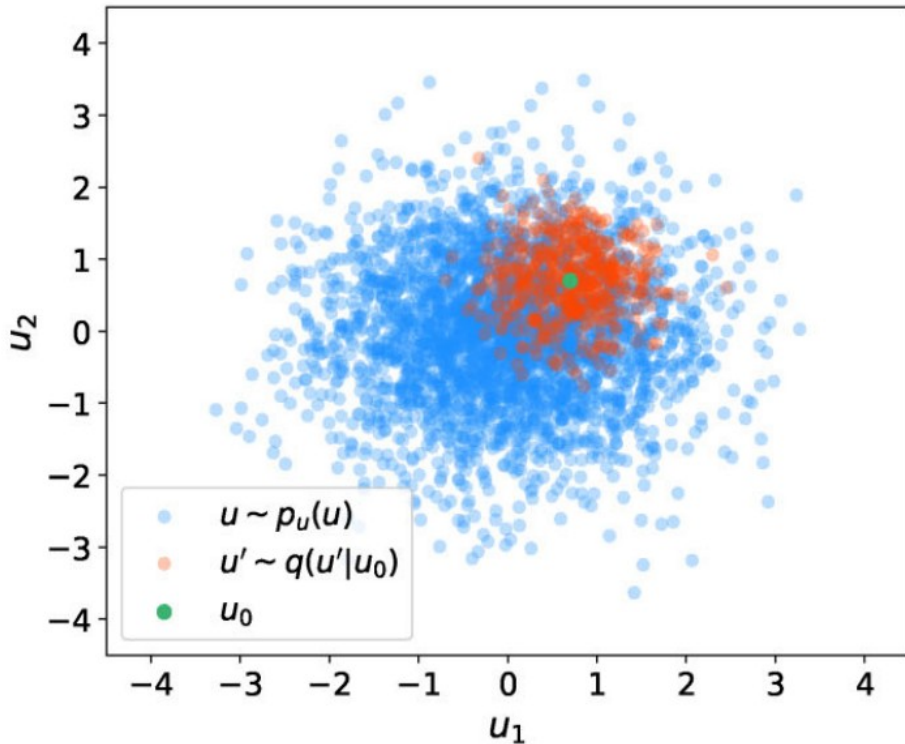


MCMC in the changed (preconditioned) coordinates

$$\alpha = \min \left(1, \frac{p_{\theta}(\theta')q(\theta|\theta')}{p_{\theta}(\theta)q(\theta'|\theta)} \right)$$

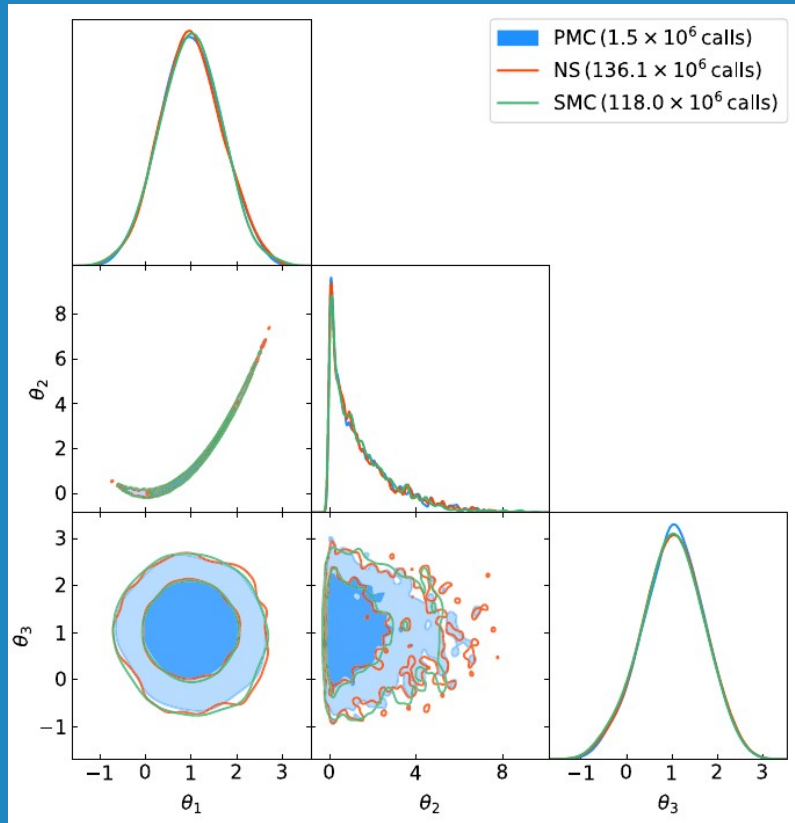
$$\alpha = \min \left(1, \frac{p_{\theta}(f^{-1}(u'))q(u|u') \left| \det \frac{\partial f^{-1}(u')}{\partial u'} \right|}{p_{\theta}(f^{-1}(u))q(u'|u) \left| \det \frac{\partial f^{-1}(u)}{\partial u} \right|} \right)$$

Proposal distribution in preconditioned vs regular coordinates

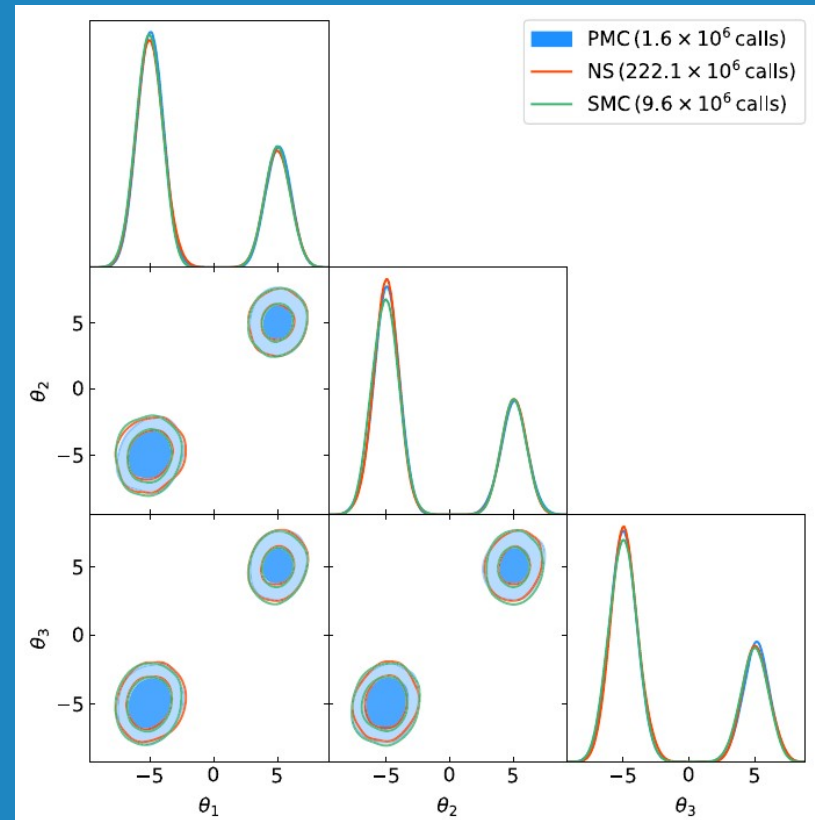


Examples

20-dim generalization of the
Rosenbrock distribution

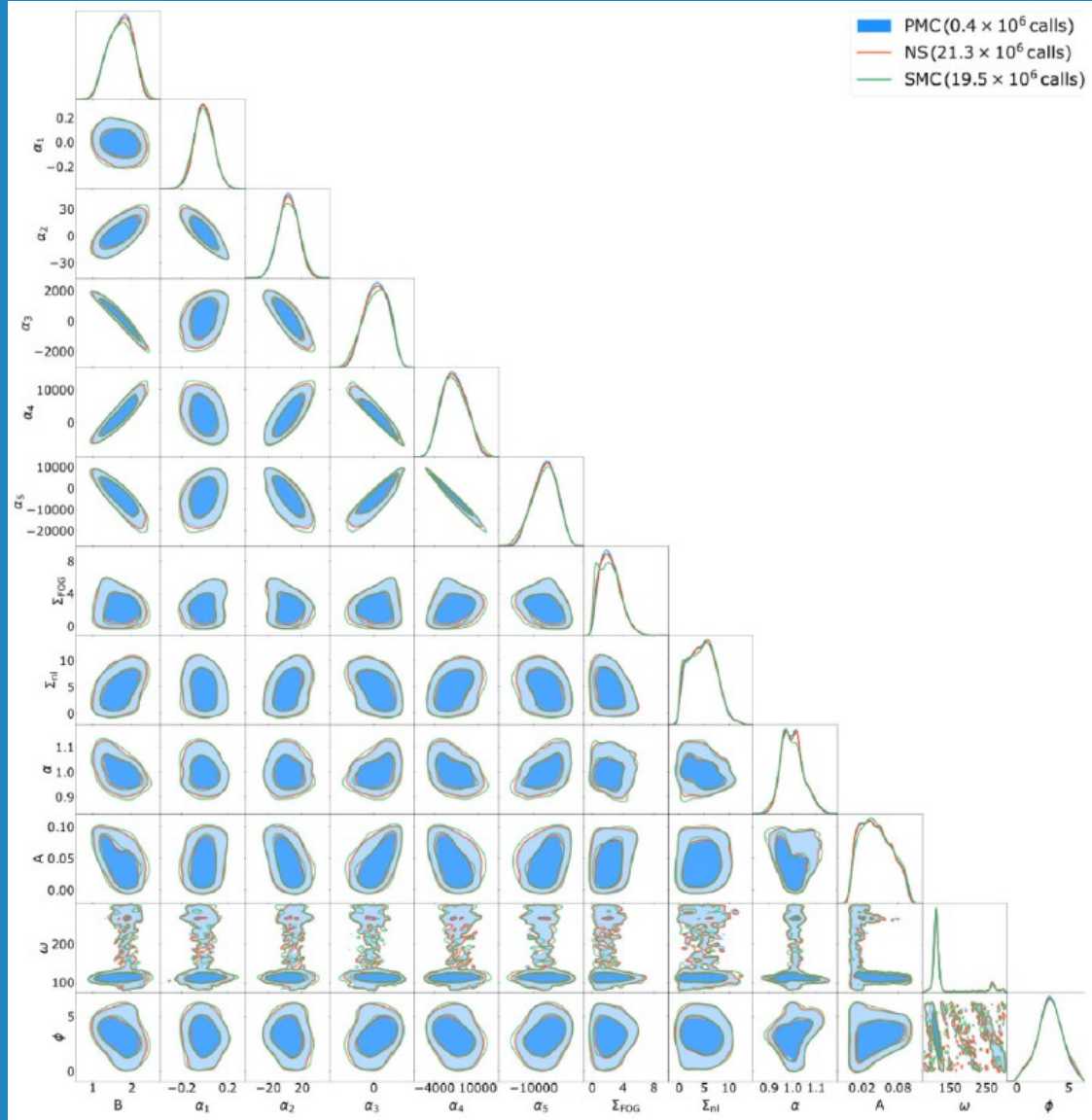


50-dim Gaussian mixture



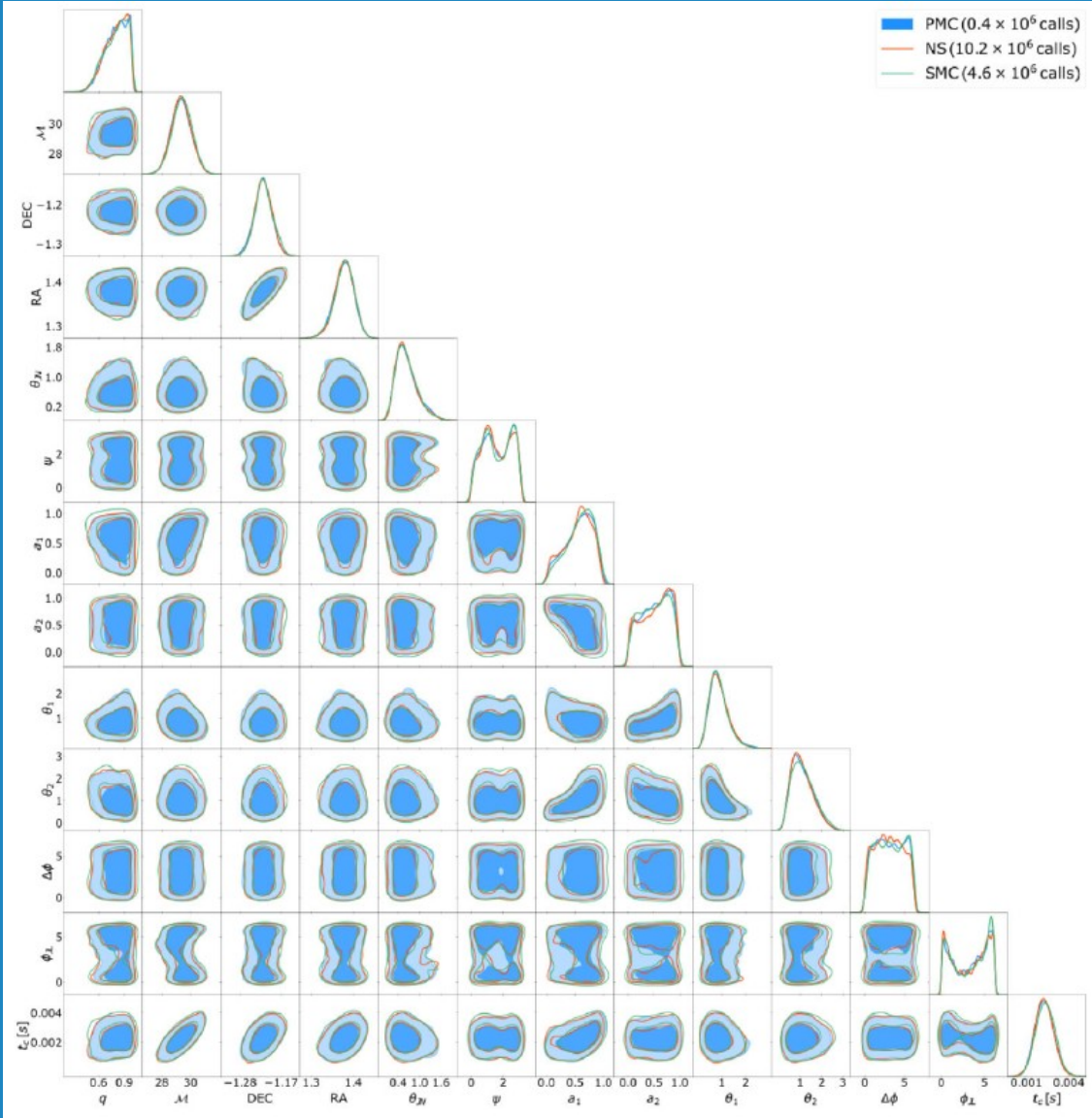
Examples

12-dim Baryon Accoustic
Oscillation features in SDSS
galaxies



Examples

13-dim gravitational wave
signal from the compact
binary coalescence



Speed

Distribution	Model evaluations ($\times 10^6$)		
	PMC	NS	SMC
Rosenbrock	1.5	136.1	118.0
Gaussian mixture	1.6	222.1	9.6
Primordial features	0.4	21.3	19.5
Gravitational waves	0.4	10.2	4.6

Thank you!

